

This is an Accepted Manuscript version of the following article, accepted for publication in:

M. Mazuela, I. Baraia, A. Sanchez-Ruiz, I. Echeverria, I. Torre and I. Atutxa, "Simple Voltage Balancing Method to Protect Series-Connected Devices Experimentally Verified in a 5L-MPC Converter," in IEEE Transactions on Industrial Electronics, vol. 65, no. 5, pp. 3699-3707, May 2018.

DOI: <https://doi.org/10.1109/TIE.2017.2760843>

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Simple voltage balancing method to protect series-connected devices experimentally verified in a 5L-MPC converter

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Abstract—This paper presents a solution for the voltage balance problem of the series-connected devices that can be applied to multilevel converters in which the series-connected devices need to block twice their switched voltage. The solution is based on two ideas, the control of the switching commands to achieve proper switching losses balance and the use of additional circuitry to achieve proper voltage balance during their blocking state. The proposed strategy is experimentally validated into a 5 Level-Multi Point Clamped (5L-MPC) full-scale converter. However, it can be used in any other converter topology in which the devices need to block twice their switched voltage.

Index Terms—Medium voltage (MV), multipoint clamped (MPC), multilevel converter, neutral point clamped (NPC), T-type converter, voltage source converter (VSC), insulated gate bipolar transistors (IGBT), series connection of semiconductors.

I. INTRODUCTION

POWER electronic converters transform electrical energy flow from one form to another, satisfying specific needs of the application. The development of power semiconductor devices has increased the number and type of applications where power converters are used. Among these applications, Medium Voltage (MV) drives [1]–[4] make the variable speed control of synchronous and asynchronous machines possible. In general, a grid side converter controls the common DC-link voltage while a machine side converter transforms the DC voltage into variable frequency and amplitude voltage [5]–[7].

Power electronic converters are mainly based on power semiconductors, being the silicon (Si) the most widely used material for their construction. The relatively narrow band gap of the silicon (1.1eV) limits the maximum voltage-blocking capability of the semiconductor to less than 10 kV. This implies

Manuscript received June 22, 2017; revised September 1, 2017; accepted September 21, 2017.

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that the voltage blocking capability of these semiconductors cannot be sufficient for real Medium/High Voltage applications [8].

The series connection of power semiconductor devices, enables the operation of well-known few-level converters (2L VSC, 2 Level-Voltage Source Converter; and 3L-NPC, 3 Level-Neutral Point Clamped Converter [9]) at voltage levels higher than the rated voltage of one single semiconductor.

In case that some semiconductors need to be series-connected, the IGBT is the preferred choice over the IGCT because the IGBT allows the control of the switching dynamics by means of the gate terminal. This makes the proper voltage balance of the series-connected IGBTs possible, avoiding the use of bulky and lossy snubber networks or at least minimizing their size [7], [10].

Fig. 1 shows typical voltage unbalances between unmatched series-connected IGBT devices. It can be observed that big time deviations can be measured at turn on and turn off switching transitions. Those time deviations lead to voltage unbalances and power-loss unbalances between the series-connected devices. As it can be observed in Fig. 1, tail current differences have a notorious negative influence on the voltage unbalance for a relatively long time (several tens of microseconds) [11], [12].

There are several proposals to improve the voltage unbalance problem between the series-connected IGBTs. Among the solutions, there are the snubber circuits [13]–[16], active clamp circuits [17] or active gate control methods [11], [12], [16], [18], [19]. Snubbers are reliable and simple solutions to achieve a proper voltage balance between the series-connected devices. However, the increase on the overall power losses make them an unattractive solution [12].

Clamp circuits limit the maximum blocking voltage of any device. The extra losses generated when the IGBT operates in the active region make them unattractive for high power and high switching frequency applications.

Active gate control methods modify the switching behavior of the IGBT controlling the charging process of the gate terminal. Thus, depending on the control strategy, synchronous switching and similar voltage slopes can be obtained between the series-connected devices. However, tail current differences or reverse recovery current differences cannot be controlled by the gate terminal and therefore, the use of some passive

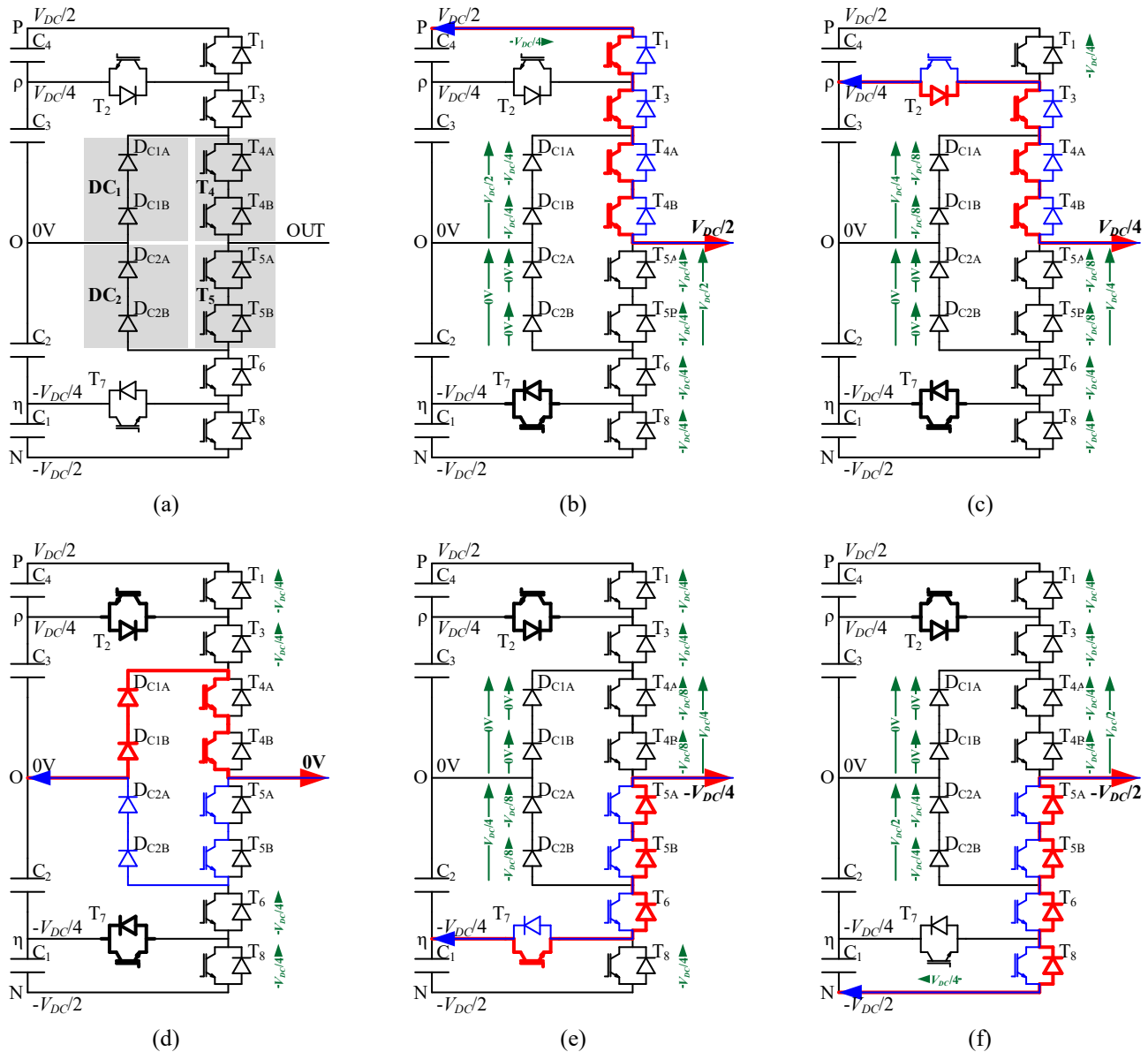


Fig. 2. 5L-MPC phase current circulation ($i_{ph} > 0$ A: red; $i_{ph} < 0$ A: blue) and blocking voltages (green) distribution for different switching states. (a) 5L-MPC phase scheme. (b) $V_{out} = V_{DC}/2$. (c) $V_{out} = V_{DC}/4$. (d) $V_{out} = 0$ V. (e) $V_{out} = -V_{DC}/4$. (f) $V_{out} = -V_{DC}/2$.

when the converter synthesizes an output voltage of $V_{DC}/2$ or $-V_{DC}/2$ they must block a voltage of $V_{DC}/2$, Fig. 2(b) and Fig. 2(f) respectively. However, when the converter is switching between $V_{DC}/4$, 0V and $-V_{DC}/4$, inner switches (T4 and T5) and clamp diodes (DC1 and DC2), operate under hard switching conditions but they only block a voltage of $V_{DC}/4$, Fig. 2(c)-(e). Therefore, the series connection of these semiconductors is not necessary in these switching states.

It is important to note that during their active switching operation, none of these series-connected devices requires additional circuitry to achieve a proper voltage balance since the series-connected devices are switching the half of their rated voltage. This facilitates the adoption of simple and effective solutions for their series connection. It can be said that the adopted solution must, basically, achieve a proper voltage

balance between the series-connected devices during their blocking state and, if possible, proper switching losses balance during their operation under hard switching conditions.

III. PROPOSED SOLUTION FOR THE PROPER OPERATION OF THE SERIES-CONNECTED IGBTs

The proposed solution for the proper operation of the series-connected IGBTs is based on two ideas: the control of the switching commands to achieve proper switching losses balance and the use of additional circuitry to achieve proper voltage balance during their blocking state, Fig. 3. This section describes the solution and the design criteria followed in the real converter [8] (6.6 kV, 1.5MW 5L-MPC with $V_{DC} = 11.2$ kV and $i_{ph,rms,1,nom} = 133$ A).

A. Control of the switching commands

In order to achieve proper switching loss balance between the series-connected IGBTs, during the switching period, one IGBT is switched on before the other IGBT and the same IGBT is switched off before the other IGBT, Fig. 4. This delay is applied by the switching manager (see Fig. 3), which receives the gate order (g_T) from the modulator, no matter the used modulation technique. With g_T , the switching manager alternatively distributes the power losses among the two series-connected devices (g_{TA} , g_{TB}), applying the delay.

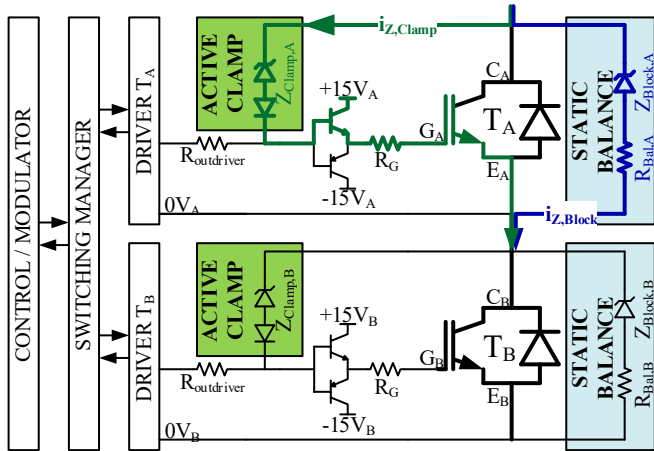
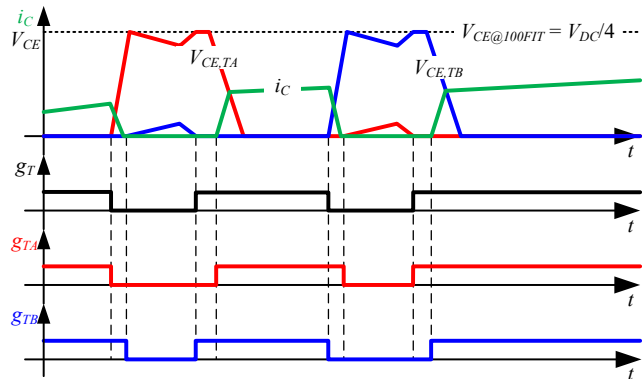
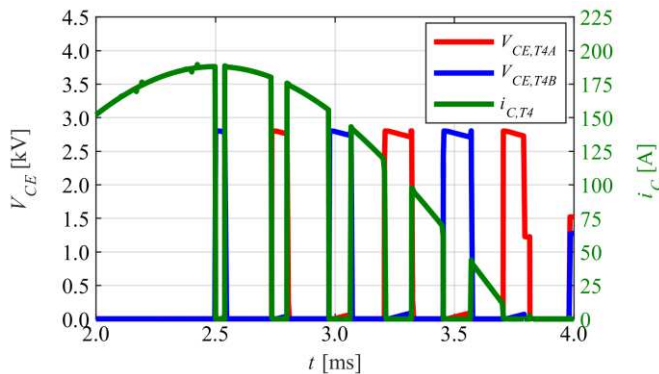


Fig. 3. Proposed switching command manager and voltage balancing circuits.



(a)



(b)

Fig. 4. Ideal switching waveforms of the command control. (a) Theoretical waveforms, where g_T represents gate command of the modulator and g_{TA} - g_{TB} represent the gate orders of the series-connected IGBTs (see Fig. 3). (b) Simulation waveforms at $V_{DC} = 11.2$ kV and $i_{ph,rms,1} = 133$ A.

Two cases (switch on and switch off) need to be distinguished in order to know which semiconductor dissipates the switching power losses:

- The switch on losses of the first IGBT are zero while the second IGBT dissipates all the turn on losses.
- During the switch off process, the first IGBT dissipates all the switch off energy while the switch off losses of the second IGBT are zero.

In the next switching period the delays are inversely applied to the series-connected IGBTs to achieve a reasonably good switching losses balance.

B. Voltage Clamp

The voltage balancing circuit has two parts: an active voltage clamp ($V_{th,Z,Clamp}$) and a static voltage balancer ($V_{th,Z,Block}$), Fig. 3. Fig. 5 shows the voltage thresholds defined by the active clamp and the voltage balancer.

The ideal behavior during the blocking state is shown in Fig. 5. In this situation, a reasonably good voltage balance between the series-connected IGBTs is achieved without the influence of the external circuit, both of them below the 100 FIT collector emitter voltage ($V_{CE@100FIT}$).

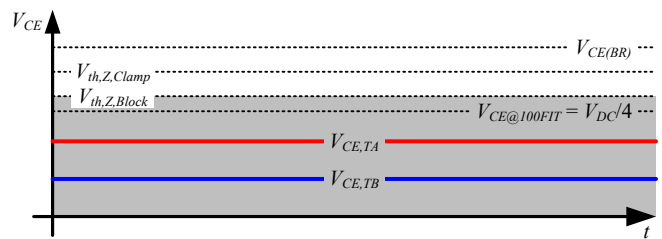


Fig. 5. Proposed voltage thresholds and natural collector-emitter V_{CE} voltage balance of series-connected IGBTs ($V_{CE,TA} < V_{th,Z,Block}$, $V_{CE,TB} < V_{th,Z,Block}$).

However, due to leakage current differences one IGBT could tend to block more voltage than the other. In this case, the static voltage balancer ($i_{Z,Block}$, Fig. 3) should clamp the maximum voltage of the IGBT with lower leakage current, Fig. 6.

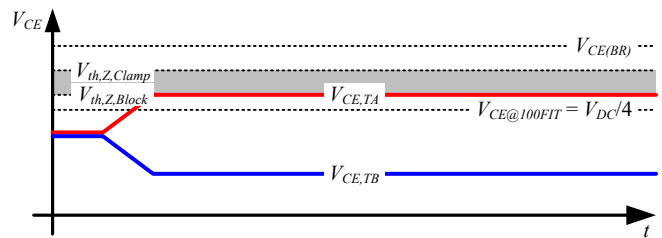


Fig. 6. Influence of the static voltage balancer ($V_{CE,TA} > V_{th,Z,Block}$).

Fig. 7 shows the voltage waveforms when the total blocking voltage increases from $V_{DC}/4$ to $V_{DC}/2$. Initially, when the total blocking voltage is $V_{DC}/4$, in the worst case, one IGBT is blocking approximately $V_{DC}/4$ while the second IGBT is close to 0V. The output capacitance of the IGBT with higher V_{CE} collector-emitter voltage is lower than the output capacitance of the IGBT with lower voltage. For this reason, when the blocking voltage passes from $V_{DC}/4$ to $V_{DC}/2$ the initial voltage slopes of the IGBTs are different, Fig. 7.

If the collector-emitter voltage of one IGBT exceeds $V_{th,Z,Block}$, the static voltage balancer injects an extra current to charge the output capacitance of the IGBT with lower voltage. Thus the collector-emitter voltage slope of the IGBT with higher voltage is reduced.

When the collector-emitter voltage of one IGBT exceeds the $V_{th,Z,Clamp}$ voltage, the active clamp circuit limits the maximum collector voltage injecting the required gate current ($i_{Z,Clamp}$, Fig. 3). During this time interval, the influence of the current injected by the static balancer can be neglected.

After the active clamping period, the static voltage balancer circuit must reduce the V_{CE} voltage from $V_{th,Z,Clamp}$ to $V_{th,Z,Block}$, Fig. 7. The time required by the static voltage balancer circuit to reach the $V_{th,Z,Block}$ voltage (τ_{Fall} , Fig. 7a and Fig. 7b) depends on the equivalent output capacitance of the IGBT and the R_{Bal} resistor.

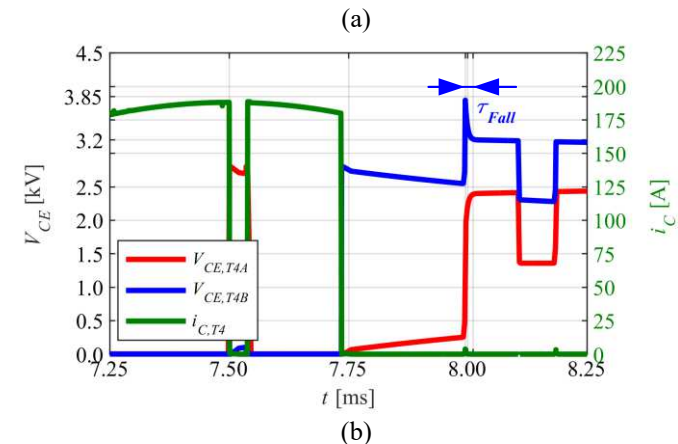
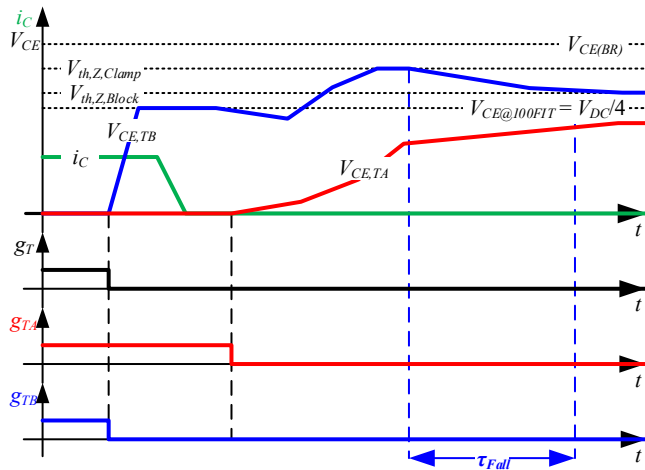


Fig. 7. Ideal IGBT switching waveforms with the voltage balance. (a) Theoretical waveforms, (b) Simulation waveforms, with $V_{DC} = 11.2$ kV, $V_{th,Z,Block} = 3200$ V and $V_{th,Z,Clamp} = 3850$ V.

In the case of the clamping diodes, there is no IGBT to control the balance of the switching losses. The switching losses balance depends on the unmatched recovery behavior of the series-connected diodes. When the pair of diodes are switching a total voltage of $V_{DC}/4$, there is no risk to exceed the rated voltage of the diodes, Fig. 8.

When the blocking voltage increases up to $V_{DC}/2$, the same active voltage clamp and voltage balancer circuits protect the diodes from excessive overvoltages, Fig. 9.

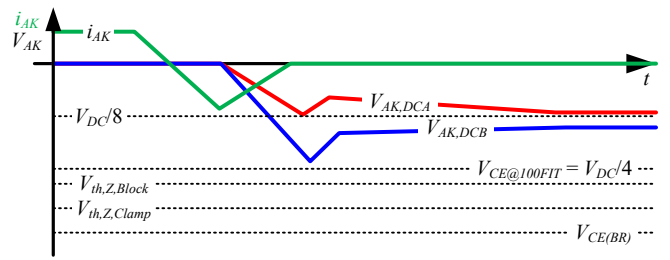


Fig. 8. Ideal diode switching waveforms with the voltage balance the control proposal, $V_{AK,DCA} + V_{AK,DCB} = V_{DC}/4$.

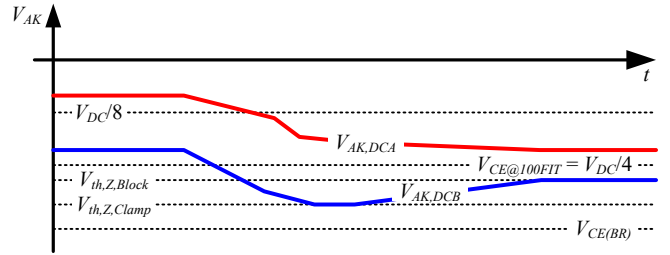


Fig. 9. Ideal diode switching waveforms with the voltage balance, $V_{AK,DCA} + V_{AK,DCB} = V_{DC}/2$.

C. Design criteria for the proposed solution

The delay time between the switching commands must guarantee that the first IGBT is completely in the on / off state, before the second IGBT receives the on / off switching command. This is the only mandatory condition. In the presented solution, during the turn on process of the second IGBT the dead time is applied. As the dead time is larger than the total switch on time, only the switch off time must be measured to define the delay time.

The active clamp should not work under nominal hard switching conditions to avoid the increase of the switch off losses in the IGBT. In consequence, the V_{CE} overvoltage must be measured during the switch off process of the IGBT at nominal current. Then, the threshold voltage of the active clamp circuit ($V_{th,Z,Clamp}$) is set at a voltage slightly higher than the measured V_{CE} overvoltage.

It should be noted that the Transient Voltage Suppressor (TVS) used for Z_{Clamp} in the active clamp circuit has a large dynamic resistor ($r_{d,Z,Clamp}$) and therefore, the real V_{CE} voltage will exceed the $V_{th,Z,Clamp}$ voltage,

$$V_{CE,max} = V_{th,Z,Clamp} + I_{Z,Clamp} \cdot r_{d,Z,Clamp}. \quad (1)$$

In order to protect the IGBT properly, a low value of $V_{th,Z,Clamp}$ is required. To do this, the V_{CE} overvoltage must be reduced and in consequence, a low leakage inductance in the bus-bar results mandatory.

The threshold voltage of the static voltage balancer circuit ($V_{th,Z,Block}$) is slightly higher than the nominal blocking voltage ($V_{DC}/4$) of the IGBT to avoid unnecessary power losses in the circuit.

The value of blocking circuit resistance R_{Bal} depends on several factors. A high value of R_{Bal} is necessary to reduce the power losses in the static voltage balancer during the turn off process of the IGBT. The overvoltage in the IGBT terminals activates the static voltage balancer and the power losses in the circuit are strongly dependant on R_{Bal} . However, a too large

value of R_{Bal} increases the voltage drop caused by the current in this resistor ($\Delta i_{leakage}$) and in consequence, the blocking voltage of the IGBT with lower leakage current. In addition, R_{Bal} and the output equivalent capacitance of the IGBT defines the time constant of the voltage fall from $V_{th,Z,Clamp}$ to $V_{th,Z,Block}$ (τ_{Fall} , Fig. 7a and Fig. 7b). In consequence, a trade-off must be made between power losses, maximum blocking voltage and the time constant.

IV. EXPERIMENTAL RESULTS

The proposed solution has been experimentally validated in a 1.5 MW back-to-back 5L-MPC converter ($V_{DC} = 11.2$ kV, $V_{out,ll,rms,1} = 6.6$ kV, $i_{out,ph,rms,1} = 133$ A, Fig. 10). As the influence of the command delay control, the active clamp circuit and the static voltage balancer can be only evaluated in the IGBT, this section is focused on the IGBT behaviour in the converter. The converter configuration and the modulation scheme for the DC-link voltage balance have been proposed in [7]. Table II summarizes the parameters of the experimental setup.

TABLE II
EXPERIMENTAL TEST BENCH PARAMETERS

Parameter	Value
DC-link rated voltage ($V_{DC,nom}$)	11.2 kV
Rated output voltage ($V_{out,ll,rms,1,nom}$)	6.6 kV
Rated output current ($i_{out,ph,rms,1,nom}$)	133 A
Semiconductors switching frequency (f_{sw})	1 kHz
IGBTs minimum conduction time ($t_{on,min}$)	8 μ s
IGBTs dead time (t_{DT})	5 μ s
Delay Time between series IGBTs (t_{delay})	2 μ s
Collector-Emitter Breakdown Voltage ($V_{CE(BR)}$)	4500 V
DC Collector Current (I_c)	150 A
Static Balancer Threshold Voltage ($V_{th,Z,Block}$)	3200 V
Static Balancer Resistor (R_{Bal})	2 k Ω (10 W)
Active Clamp Threshold Voltage ($V_{th,Z,Clamp}$)	3850 V

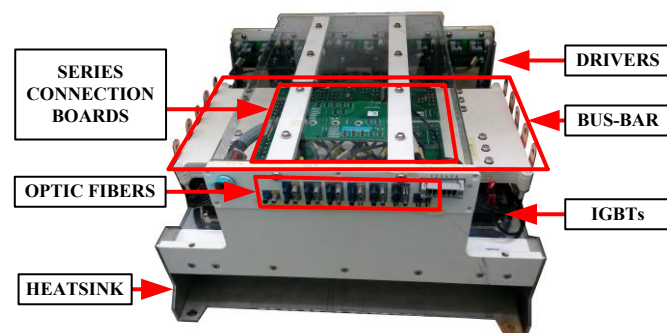


Fig. 10. Developed phase power stack.

As described in [7], each 5L-MPC phase branch is composed of ten 4.5 kV/150 A IGBT modules, which are indistinctly used as IGBT-diode pairs and clamping diodes, DC_1 and DC_2 . The voltage balancing circuits are connected to the series-connected devices DC_1 , DC_2 , T_3 , T_4 , T_5 and T_6 , Fig. 2. Considering the output capacitance of the IGBT and the R_{Bal} resistor, the V_{CE} voltage requires about 7 μ s to converge to $V_{th,Z,Block}$ from

$V_{th,Z,Clamp}$. Considering the dynamic resistance of the used TVS devices, V_{CE} voltages up to 4300 V are expected in the worst case scenario. This voltage is quite close from the breakdown voltage of the IGBT/Diodes. However, the large leakage inductance in the bus-bar (up to 800 nH) makes no possible the reduction of the $V_{th,Z,Clamp}$ voltage. The total power losses in each auxiliary circuit is less than 10 W.

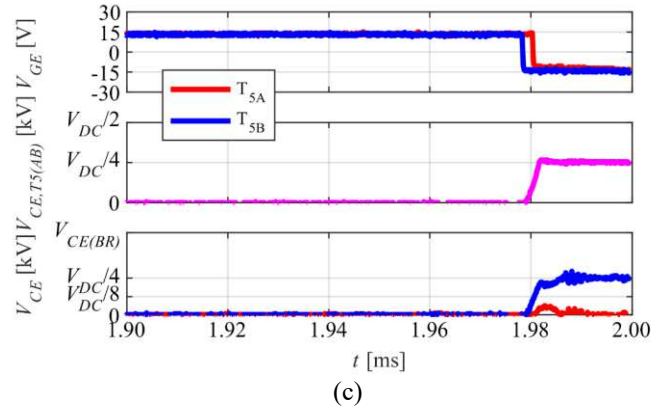
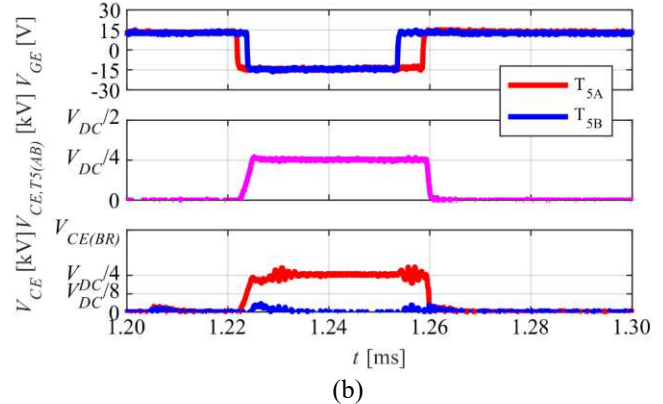
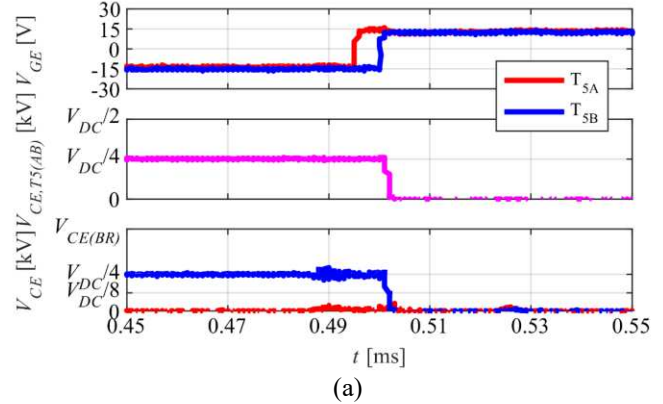


Fig. 11. Experimentally measured gate-emitter voltages (V_{GE}), total blocking voltage ($V_{CE,TS(AB)}$) and collector-emitter voltages (V_{CE}) during a switching losses distribution sequence, with $V_{DC} = 8$ kV and $\cos\phi = 0$. (a) T_{5B} assumes the switch-on losses. (b) T_{5A} assumes the switch-off losses and switch-on losses consecutively. (c) T_{5B} assumes the switch-off losses.

A. Control of the switching commands

Fig. 11 shows the individual switching commands, the total switched voltage and the individual collector voltages of the series-connected T_{5A} and T_{5B} IGBTs. Fig. 11a shows a switch

on process in which T_{5A} is turned on before T_{5B} . As the current cannot circulate until both of them are in the on state, T_{5B} dissipates all the turn on energy.

Fig. 11b shows that T_{5A} is switched off before T_{5B} . In this case, the circulating current is interrupted by T_{5A} ; thus, all the switch off energy is dissipated by this IGBT. Fig. 11b also shows that during the next switch on process, T_{5A} is turned on later than T_{5B} ; thus T_{5A} dissipates now all the turn on energy. It is important to note that the effective turn on delay between series-connected IGBTs is larger in this case because the dead time (t_{DT}) is applied between the two turn on commands. Finally, Fig. 11c shows the next switch off process, in which T_{5B} assumes the turn off energy losses.

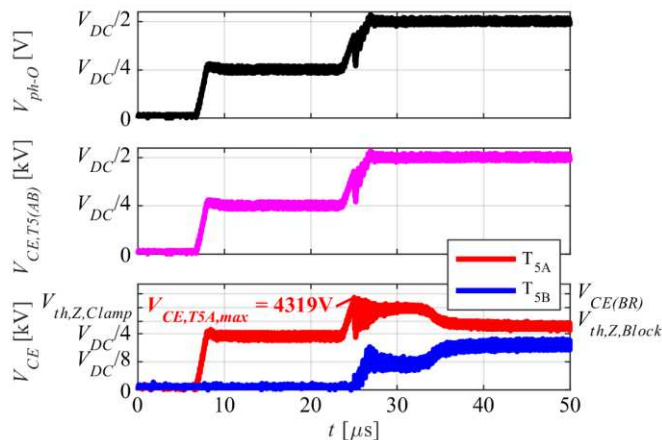


Fig. 12. Experimentally measured phase voltage (V_{ph-o}), total blocking voltage ($V_{CE,T5(AB)}$) and collector-emitter voltages (V_{CE}), with static voltage balancer circuit actuation during a blocking voltage transition from $V_{CE,T5(AB)} \approx V_{DC}/4$ to $V_{CE,T5(AB)} = V_{DC}/2$, with $V_{DC} = 11$ kV, $\cos\phi = 0.88$, $V_{th,Z,Block} \approx 3200$ V and $V_{th,Z,Clamp} \approx 3850$ V.

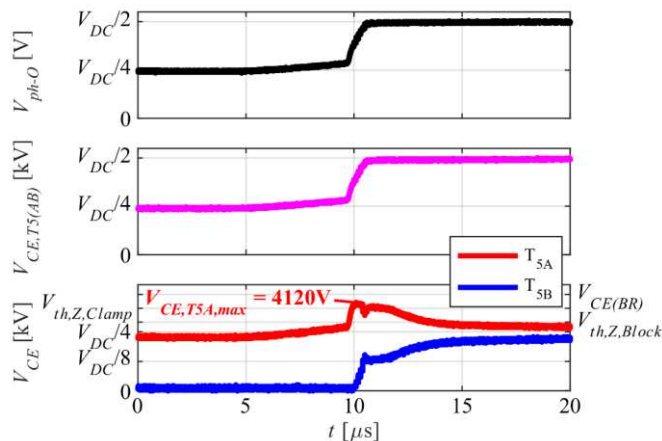


Fig. 13. Experimentally measured phase voltage (V_{ph-o}), total blocking voltage ($V_{CE,T5(AB)}$) and collector-emitter voltages (V_{CE}), with active clamping circuit actuation during a blocking voltage transition from $V_{CE,T5(AB)} \approx V_{DC}/4$ to $V_{CE,T5(AB)} = V_{DC}/2$, with $V_{DC} = 11$ kV, $\cos\phi = 0$, $V_{th,Z,Block} \approx 3200$ V and $V_{th,Z,Clamp} \approx 3850$ V.

B. Voltage clamp

Fig. 12 ($\cos\phi = 0.88$) and Fig. 13 ($\cos\phi = 0$) show the phase voltage (V_{ph-o}) and the V_{CE} voltages of the T_{5A} - T_{5B} IGBTs with $V_{DC} = 11$ kV ($V_{DC}/4 = 2.75$ kV). The phase voltage (V_{ph-o}) changes from $0V$ to $V_{DC}/4$ and $V_{DC}/2$. This phase voltage is the voltage that must be blocked by the series-connected T_{5A} - T_{5B}

IGBTs ($V_{CE,T5(AB)}$). In this transition from $0V$ to $V_{DC}/4$ (Fig. 12), T_{5A} assumes the total blocking voltage because it is turned off before T_{5B} . When the total blocking voltage increases to $V_{DC}/2$ (Fig. 12 and Fig. 13) the auxiliary circuits protect T_{5A} limiting its maximum V_{CE} voltage. As expected, after the active clamping period, its V_{CE} voltage reaches the $V_{th,Z,Block}$ voltage.

It can be observed that during the transient the achieved maximum V_{CE} voltage is considerably higher than the $V_{th,Z,Clamp}$ voltage due to the dynamic resistor of the TVS. As described previously, in the worst case scenario, the maximum V_{CE} voltage is about 4.3 kV.

Finally, Fig. 14 shows the phase voltage during a fundamental period of the output voltage. In addition, the total blocking voltage of the series-connected IGBTs is shown. The influence of the alternating switching commands on the power loss distribution and the influence of the auxiliary circuits can be observed.

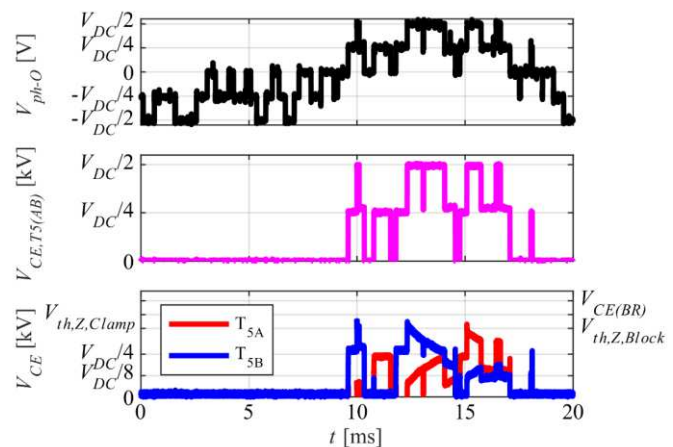


Fig. 14. Experimentally measured phase voltage (V_{ph-o}), total blocking voltage ($V_{CE,T5(AB)}$) and collector-emitter voltages (V_{CE}), with static voltage balancer circuit actuation during a fundamental period of the output voltage, with $V_{DC} = 8$ kV, $\cos\phi = 0$, $V_{th,Z,Block} \approx 3200$ V and $V_{th,Z,Clamp} \approx 3850$ V.

V. CONCLUSION

This paper presents an easy and reliable solution for the voltage balance problem of the series-connected IGBT/Diodes in the 5L-MPC converter.

It is important to note that during the hard switching process these devices can operate as non-series-connected devices. Therefore, solutions to deal with asynchronous switchings and differences in tail and recovery currents are not necessary. This simplifies the problem related to the series connection of switching devices. The proposed solution can be applied to any other multilevel topology in which the series-connected devices need to block twice their switched voltage (5L-SMC, T-Type...).

Basically, the proposed solution consist of the control of the switching commands to achieve a proper switching loss balance and the use of clamp circuits to protect the devices during the off state.

The proposed method has been experimentally evaluated and very promising results have been obtained. Hard switchings have been controlled by the gate command delays and active

clamping and static balancer circuits have properly protected the devices.

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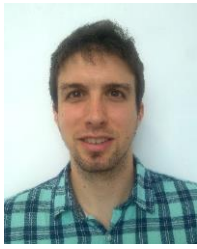
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